

Effects of landscape compositional heterogeneity and spatial autocorrelation on environmental niche and dispersal in simulated organisms

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Abstract

Local adaptation, environmental tolerance, and dispersal mutually influence the evolution of one another and each are in turn influenced by landscape spatial structure. While each of the three have been investigated frequently in isolation in relation to spatial structure, the three have rarely been considered together. In this study, we explored how the magnitude of landscape environmental heterogeneity (compositional heterogeneity), and environmental spatial autocorrelation jointly affect the evolution of environmental niche optima, tolerance, dispersal frequency, and dispersal distance using a spatially explicit individual based model simulating organisms living, reproducing, and dispersing within grid-based fractal landscapes. Compositional heterogeneity tended to have the strongest influence over patterns while spatial autocorrelation typically played a mediating role. We found that niche adaptation and dispersal patterns were driven by a balance between pressure to avoid risk imposed by spatial heterogeneity and pressure to hedge against risk imposed by temporal environmental fluctuations. Dispersal frequency and dispersal distance were affected differently by spatial structure, underscoring the importance of considering the two independently.

1 **Effects of landscape compositional heterogeneity**
2 **and spatial autocorrelation on environmental**
3 **niche and dispersal in simulated organisms**

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5 **Abstract**

6 Local adaptation, environmental tolerance, and dispersal mutually influence the evolution of one
7 another and each are in turn influenced by landscape spatial structure. While each of the three
8 have been investigated frequently in isolation in relation to spatial structure, the three have rarely
9 been considered together. In this study, we explored how the magnitude of landscape environ-
10 mental heterogeneity (compositional heterogeneity), and environmental spatial autocorrelation
11 jointly affect the evolution of environmental niche optima, tolerance, dispersal frequency, and
12 dispersal distance using a spatially explicit individual based model simulating organisms living,
13 reproducing, and dispersing within grid-based fractal landscapes. Compositional heterogeneity
14 tended to have the strongest influence over patterns while spatial autocorrelation typically played
15 a mediating role. We found that niche adaptation and dispersal patterns were driven by a balance
16 between pressure to avoid risk imposed by spatial heterogeneity and pressure to hedge against
17 risk imposed by temporal environmental fluctuations. Dispersal frequency and dispersal distance
18 were affected differently by spatial structure, underscoring the importance of considering the two
19 independently.

20 **Introduction**

21 Organisms exist within environments which vary over both time and space. Organisms can cope
22 with spatial variation in their environments by adapting their niche optima to local conditions.
23 Given adequate genetic variation in the population, such adaptation can occur quickly. However,
24 successful adaptation requires organisms to cope with short term temporal variation in the envi-
25 ronment (Hoffmann and Sgrò, 2011). Organisms can deal with temporally variable environments
26 by adapting their tolerances to local temporal variance. Alternatively, organisms can avoid pe-
27 riods of unfavorable conditions or hedge reproductive bets via dispersal (Venable and Brown,
28 1988; Kisdi, 2002), reducing the need to tolerate temporal variance in the environment (Bonte
29 et al., 2012). However, because dispersal requires organisms to move through space and settle in
30 new habitats, organisms relying on dispersal to avoid temporal environmental variance must be
31 sufficiently capable of tolerating the spatial heterogeneity they encounter in their environments
32 (Futuyma and Moreno, 1988; Bonte et al., 2012). Tolerance to this spatial variation may not
33 necessarily be conferred by tolerance to temporal variation as the environmental factors that
34 vary over space may be different from those that vary over time. Since tolerances are critical
35 to the ability of organisms both to stay in place and disperse, both strategies are subject to
36 constraints (Bonte et al., 2012; Hillaert et al., 2015) imposed by trade-offs between tolerance to
37 environmental variation and performance under optimal conditions Morin and Chuine (2006);
38 Ravigné et al. (2009); Herren and Baym (2022), or trade-offs between tolerances to variation in
39 different environmental factors. Moreover, the evolution of local adaptation and environmental
40 tolerances are themselves affected by and organism’s dispersal behavior through its effects on
41 immigration and gene flow (Kirkpatrick and Barton, 1997; Ronce and Kirkpatrick, 2001; Lenor-
42 mand, 2002; Billiard and Lenormand, 2005; Bridle et al., 2010, 2019). Dispersal and movement
43 behavior in turn is informed by the risks imposed by spatial environmental heterogeneity and
44 the selection it imposes, meaning that the evolution of local adaptation and environmental toler-
45 ances are dependent on spatial context (Bonte et al., 2006; Richardson et al., 2014; Forester et al.,
46 2016), including the magnitude of compositional environmental heterogeneity and its spatial ar-
47 rangement (Fahrig, 2017). This dependence on on spatial context has important implications for
48 conservation, particularly in the face of climate change, as certain spatial structures may help or
49 hinder local adaptation (Claudino and Campos, 2014), range shifts (Burton et al., 2010; Synes
50 et al., 2015; Årevall et al., 2018), and recolonization of habitat after disturbance (Leimar and
51 Norberg, 1997), making a thorough understanding of the effects of spatial structure on adaptation
52 and dispersal key to creating effective conservation strategies (Holt and Barfield, 2011; Årevall
53 et al., 2018).

54 Studies investigating dispersal and adaptation commonly adopt a mechanistic modeling ap-

55 proach due to the large temporal and spatial scales such processes can occur over, the difficulty
56 of observing them in nature, and the difficulty of experimentally manipulating conditions in the
57 field (Hanski, 2015; Ovaskainen et al., 2019). A mechanistic modeling approach has the advan-
58 tage of allowing detailed experimental control over conditions while also enabling direct insight
59 into causal mechanisms underpinning patterns by explicitly ecological and evolutionary processes
60 (Cabral et al., 2017; Hanski, 2015; Higgins et al., 2012). While numerous modeling studies have
61 explored aspects of local adaptation (García-Dorado, 1987; Bridle et al., 2010; Claudino and
62 Campos, 2014; Kisdi et al., 2020), tolerance and niche breadth (Hillaert et al., 2015; Sieger et al.,
63 2019; Kisdi et al., 2020), and dispersal (Hamilton and May, 1977; Gros et al., 2006; Duputié and
64 Massol, 2013; Hillaert et al., 2015), few studies consider all three simultaneously. In their review
65 of individual-based models examining eco-evolutionary dynamics, Romero-Mujalli et al. (2019)
66 found no studies which simultaneously modeled the evolution of local adaptation, dispersal, and
67 phenotypic plasticity. Moreover, the authors also noted that studies focused on local adaptation
68 were often not spatially explicit (e.g. (Kisdi et al., 2020)). Modeling studies on local adaptation
69 which do consider spatial environmental variation tend to do so only in very simplified manners,
70 often assuming simple linear gradients e.g. (Hillaert et al., 2015; Leidinger et al., 2021). Mean-
71 while, studies modeling dispersal often explicitly consider spatial structure, but typically assume
72 a binary habitat-non-habitat dichotomy e.g. (Gros et al., 2006; Claudino and Campos, 2014).
73 Such assumptions are problematic, particularly for terrestrial environments, as environmental
74 shifts in space are often gradual and many species exploit multiple habitat types (Hein et al.,
75 2003; Jules and Shahani, 2003), meaning it may be more appropriate in many cases to model
76 landscapes as fractal environmental gradients or habitat mosaics (Fischer and B. Lindenmayer,
77 2006; Franklin and Lindenmayer, 2009). Sieger and Hovestadt (2020) used continuous fractal
78 landscapes to explore the effect of the ratio of temporal to spatial heterogeneity on the evolution
79 of dispersal frequency using an individual-based model which notably modeled niche optimum,
80 tolerance, and dispersal together as evolving traits. While the authors considered the magnitude
81 of variation in patch environments (compositional heterogeneity), they did not explore the effects
82 of spatial configuration despite its importance as a component of environmental spatial structure
83 Fahrig (2017). Moreover, the authors assumed only random global dispersal, and did not con-
84 sider how environmental heterogeneity could affect other components of dispersal strategy such
85 as dispersal distance, which may be affected by spatial heterogeneity independently of dispersal
86 frequency (Gros et al., 2006; Bonte et al., 2010). In this study, we use an extended version of the
87 model of Tardanico and Hovestadt (2023), developed as an extension of the model of (Sieger and
88 Hovestadt, 2020), in order to systematically explore the effects of landscape structure on adap-
89 tation and dispersal strategy of annual asexual organisms with varying environmental niches and
90 dispersal probabilities living, reproducing, and competing in continuous fractal landscapes. We

91 extended the model by considering both temporally static and temporally variable patch en-
92 vironment attributes as well as by permitting dispersing organisms to choose between random
93 global or nearest neighbor dispersal strategies, thus incorporating dispersal distance explicitly
94 into the model. We specifically ask how the magnitude of spatial environmental variation, or
95 compositional heterogeneity, and spatial environmental autocorrelation jointly affect the evolu-
96 tion of environmental niche optima, tolerances to environmental variation, dispersal frequency,
97 and preference for shorter or longer distance dispersal, including the evolution of syndromes in
98 these traits. In addition to data on organism traits such as niche optima, tolerances, and dis-
99 persal behavior, our model also records information on organism lineages and thus may be used
100 to explore diversity patterns, which we previously explored in (Tardanico and Hovestadt, 2023).
101 This study, however, will restrict itself to dealing with patterns of adaptation in organism traits.

102 **Methods**

103 We used the model which we developed for our previous study (Tardanico and Hovestadt, 2023).
104 As we made no modifications to the simulation model from our previous study, the description
105 of the model and its mechanics have been recycled from Tardanico and Hovestadt (2023).

106 **Landscape properties**

107 Landscapes consist of grids of habitat patches. Patches possess two attributes one representing
108 patch temperature (T) and second attribute (H) representing an additional, unspecified envi-
109 ronmental variable (e.g. a soil property). Spatial distributions for the two patch attributes were
110 generated via an R implementation of the spatially autocorrelated landscape generation algorithm
111 from Saupe (1988). This algorithm is capable of generating fractal landscapes with varying de-
112 grees of spatial autocorrelation between grid cell values depending on the value of the Hurst
113 index parameter. Landscapes generated with this algorithm are toroid and opposite edges con-
114 nect seamlessly to each other, thereby preventing edge effects from occurring at landscape edges.
115 In this study, all landscapes were generated with a Hurst index of either 0 or 1. A Hurst index
116 of 1 produces completely spatially autocorrelated landscapes where patches always have similar
117 environments to their immediate neighbors, while a Hurst index of 0 produces a largely random
118 spatial distribution of patch environments. Spatial distributions for the two patch attributes are
119 generated independently, meaning that T and H attributes do not necessarily correlate with each
120 other spatially. However, T and H spatial distributions for the same landscape were generated
121 with matching generation parameters, including the Hurst index. Thus a landscape with a highly
122 autocorrelated spatial distribution for the T attribute will always have an equally spatially auto-
123 correlated H attribute distribution. Values for patch environmental attributes were drawn from

124 a normal distribution and standardized to a mean of 0 and a standard deviation of 1, such that
125 the average frequency of different patch environment values was constant regardless of spatial
126 configuration. Landscape dimensions were set at 20 by 20 patches for a total of 400 patches in
127 a landscape. These dimensions were chosen in order to limit computation time while still being
128 large enough for structure driven patterns to emerge. Landscape compositional heterogeneity,
129 the magnitude of spatial variation in the T and H attributes was controlled by the simulation
130 parameter G . By multiplying patch attribute values by G , the range of values could be expanded
131 or reduced. In addition to varying spatially, the T attribute fluctuates over time such that the
132 T attribute for patches varies from one time step to the next. Fluctuations in T are global and
133 affect all patches in a landscape equally. Fluctuations in T are normally distributed with a mean
134 of 0 and a standard deviation of 1 and modify patch T attributes by adding the value of the
135 fluctuation to the patch's T attribute.

136 **Organism properties**

137 Patches are inhabited by populations of asexual organisms belonging to lineages which behave as
138 a guild of ecologically similar species who compete with each other within a patch. In addition to
139 possessing a “taxonomic” identity, lineages possess varying environmental niches and dispersal
140 tendencies, which serve to differentiate lineages functionally from one another. Organism niches
141 are modeled as Gaussian curves whose center and spread are defined by a niche optimum and
142 tolerance trait respectively. Organisms possess separate optimum and tolerance traits for T and
143 H . T niche optimum and tolerance are represented by the T_{opt} and T_{tol} traits respectively, while
144 H optimum and tolerance represented by the H_{opt} and H_{tol} traits. Organisms also possess two
145 dispersal traits, P_{disp} , which defines the probability of an organism dispersing from its natal
146 patch, and P_{global} which defines an organism's preference for one of two possible dispersal modes.
147 Dispersal is explained further in the section below. Organism traits are summarized in table 1.
148 Trait values are generated when a lineage first appears in a landscape by drawing random values
149 from statistical distributions. Niche optima are drawn from a normal distribution with a μ of 0
150 and σ equal to G . Tolerance traits are drawn from a log-normal distribution with a μ and σ of 0
151 and 1 respectively. Dispersal traits are drawn from a uniform distribution with a minimum of 0
152 and a maximum of 1. Organism traits are summarized in table 1.

153 **Dispersal**

154 Organisms can disperse from their natal patches to other patches. Individual organisms may
155 disperse once during their life cycle. Whether or not an organism disperses from its natal patch
156 is determined by drawing a random number from a uniform distribution and comparing the value
157 with an organism's P_{disp} trait. If the random number is less than or equal to the organism's P_{disp}

Table 1. Organism Traits & Initialization Distribution Parameters. Modified from Tardanico and Hovestadt (2023).

Trait	Symbol
Temperature Optimum	T_{opt}
Temperature Tolerance	T_{tol}
Habitat Optimum	H_{opt}
Habitat Tolerance	H_{tol}
Dispersal Chance	P_{disp}
Dispersal Mode Preference	P_{global}

158 trait value, the organism will disperse. Dispersing organisms must then choose a dispersal mode.
159 Two different modes of dispersal are possible within this model, serving as short and long distance
160 modes. We chose to explicitly incorporate dispersal distance as a separate trait due to previous
161 research indicating that landscape spatial structure affects dispersal distance differently from
162 dispersal frequency (Gros et al., 2006). Organisms can disperse via nearest neighbor dispersal or
163 random global dispersal. We chose these two dispersal methods because they are computationally
164 lightweight, simple to implement, and already in widespread use in modeling studies (Kisdi
165 et al., 2020). The dispersal mode is selected by drawing a random number from a uniform
166 distribution between 0 and 1 and comparing its value with an organism’s P_{global} trait. If the
167 number’s value is less than or equal to the organism’s P_{global} trait, the organism disperses via
168 random global dispersal. If not, the organism disperses via nearest neighbor dispersal. In nearest
169 neighbor dispersal, an organism moves to a random patch with the coordinates $x + p$ and $y +$
170 q , where x and y are the coordinates for the natal patch and p and q are integers between -1
171 and 1. If the target patch’s coordinates are outside the bounds of the landscape, the organism
172 is instead moved to the opposite side of the landscape. In random global dispersal, a random
173 patch within the landscape is selected as the target patch. In both dispersal modes, the target
174 patch must have different coordinates from the natal patch and will be re-selected if the target
175 coordinates leave a dispersing organism in its natal patch.

176 Organism life-cycle

177 Organisms have annual life cycles with complete replacement of the population at the end of a
178 generation. Life cycles consist of discrete reproduction, competition, and dispersal phases. During
179 the reproductive phase, organisms reproduce asexually to produce offspring with identical traits
180 to their parents. The number of offspring is drawn from a Poisson distribution, with the expected
181 reproductive output determined by an organism’s fitness within its patch environment within a
182 given time step as given by equation 1. Here, E_{fert} is the expected number of offspring, R_0
183 is an organism’s intrinsic maximum expected offspring (kept at a constant value of 15), T_{patch}
184 and H_{patch} are the temperature and habitat values for a given patch. Reproductive output is
185 additionally limited by a trade-off between tolerance and maximum expected offspring, meaning

186 that organisms with broader tolerances produce fewer offspring on average. This trade-off serves
187 to prevent organisms from having infinitely large tolerances. The strength of this trade-off is
188 determined by the trade-off parameter a . (Chaianunporn and Hovestadt, 2012; Sieger et al.,
189 2019); lower values produce stronger trade-offs. As the effect of varying a is functionally the
190 same as the effect of varying the strength of G , a is kept at a constant value of 3 in this study.
191 After reproduction, offspring undergo a maturation phase in which they compete on an equal
192 basis with other offspring within the same patch. Survival of the competition phase is density
193 dependent and regulated via the Beverton-Holt equations (Equations 2. and 3.; Beverton &
194 Holt 1957), where S_A is the expected surviving offspring, L_0 is the total offspring, and K is the
195 carrying capacity of a patch if all organisms in the patch have an E_{fert} equal to R_0 and thus
196 perfect fitness. Note that because patch carrying capacity is affected by E_{fert} , maladaptation
197 may reduce the realized carrying capacity of a patch. The value of K is set at 150 individuals,
198 which allows for relatively stable patch populations while maintaining low computation time.
199 The number of surviving offspring are determined by drawing a random number from a binomial
200 distribution with a mean of S_A . Surviving offspring are then able to disperse to a new patch and
201 start the cycle anew.

$$E_{fert} = R_0 \cdot e^{\frac{-(T_{patch} - T_{opt})}{2T_{sd}^2}} \cdot e^{\frac{-(H_{patch} - H_{opt})}{2H_{sd}^2}} \cdot e^{\frac{-T_{sd}^2}{2\alpha^2}} \cdot e^{\frac{-H_{sd}^2}{2\alpha^2}} \quad (1)$$

$$S_A = \frac{1}{1 + a \cdot L_0} \quad (2)$$

$$a = \frac{R_0 - 1}{K \cdot R_0} \quad (3)$$

202 Immigration from external sources

203 New organisms can immigrate into the landscape from the outside. The number of new immi-
204 grants is randomly drawn from a Poisson distribution with an expected value of E_{immi} . In our
205 simulations, E_{immi} is set at a constant expected value of 2.5 immigrants per patch. This amounts
206 on average to approximately 0.0011% of the expected local offspring production for a patch with
207 a perfectly adapted population at carrying capacity. Immigrants are generated with randomized
208 traits within a patch and added to the new generation along with existing offspring. Since immi-
209 grants arrive in the landscape from places which may have considerably different environmental
210 conditions, immigrant niche optima are drawn from broader distributions than those used for
211 initialization. Statistical distribution parameters for immigrant traits are summarized in table 2.

Table 2. Immigrant trait distributions and parameters. From Tardanico and Hovestadt (2023).

Trait	Distribution	Parameters
T_{opt}	Uniform	$\mu = T_{trend}, \sigma = 1.5 * G$
T_{tol}	Log-Normal	$\mu = 0, \sigma = 1$
H_{opt}	Uniform	$\mu = 0, \sigma = 1.5 * G$
H_{tol}	Log-Normal	$\mu = 0, \sigma = 1$
P_{disp}	Uniform	0,1
P_{global}	Uniform	0,1

212 0.1 Experiment design

213 Landscapes were initialized from text files containing spatial distributions for the two patch
214 attributes. Landscapes were initially empty with no pre-existing populations and were then
215 allowed to be colonized by immigrant organisms over the course of the simulation. As with before,
216 simulations were run for a total of 10,000 time steps. Simulations were run once for each landscape
217 in a set for a total of 30 unique replicates. Fluctuations for each time step were generated at
218 initialization. To ensure replicability, each replicate in a scenario was run with a unique, preset
219 random number generator seed. We ran 7 different G scenarios ($G \in 0.05, 0.1, 0.3, 0.7, 1, 1.3, 1.7$)
220 and 2 Hurst index scenarios (0 and 1) for a total of 14 different scenarios. The simulation
221 program recorded means and variances for trait values and fitness at each time step for entire
222 landscapes, as well as a census of each individual organism in a landscape at the 10,000th timestep,
223 including its lineage identity, trait values, and the patch it inhabited. The program then used
224 the census data to calculate mean trait values and fitness for each patch in the landscape. We
225 calculated two fitness metrics in this study, an organism’s expected number of offspring, and the
226 expected proportion of the maximum possible offspring. Model parameters used in this study
227 are summarized in table 3.

Table 3. Summary of model parameters used in the experiment.

Parameter	Symbol	Value
Landscape dimensions		20*20 patches
Total simulation time-steps	t_{max}	10,000
Niche breadth trade-off	a	3
Patch Expected immigrants	E_{immi}	2.5
Gradient strength multiplier	G	$\in 0.05, 0.1, 0.3, 0.7, 1, 1.3, 1.7$
Landscape Hurst Index	$Hurst$	$\in 0, 1$

228 0.2 Data analysis

229 We analyzed simulation output data in R (R Core Team, 2020). Analysis was conducted for
230 individual organisms at time step 10,000 belonging to lineages with total landscape populations
231 larger than 50 individuals. We did this in order to restrict the analysis to lineages with established
232 populations and eliminate transient lineages with extreme or highly mismatched traits which were
233 likely to die out soon after appearing in the landscape. Due to the large size of the data set, we

234 opted to sample 10,000 individuals from each scenario. In some cases, environmental fluctuations
235 caused population crashes at the final time step, meaning there were not enough individuals to
236 obtain a full sample of 10,00 individuals. This resulted in a data set with a total of 139,477
237 observations. We assessed the data visually using ggplot2 R package (Wickham, 2016) and
238 evaluated R^2 correlations between the six organism traits using the ggally package (Schloerke
239 et al., 2024). We did not make use of statistical significance tests due to their lack of meaning
240 within a mechanistic modeling context and their unreliability due to extreme sensitivity when
241 sample sizes are extremely large (White et al., 2014).

242 Results

243 0.3 Organism Traits

244 Organism traits responded diversely to G and the Hurst index (Fig. 1). Since these patterns were
245 largely identical at the landscape level and when aggregated at the patch level, this subsection
246 will focus on landscape level patterns. Niche optima traits T_{opt} and H_{opt} matched the frequency
247 distributions for their respective patch attributes, with median values close to 0 and variances
248 which increased with increasing G . Median T tolerance (T_{tol}) showed little variation with G , but
249 did increase in variance. T_{tol} was unaffected by the Hurst index. H tolerance (H_{tol}) increased in
250 both median and variance with greater G . This increase was monotonic under a Hurst index of
251 1, while under a Hurst index of 0 the increase was non-monotonic between $G=0.05$ and $G=0.3$.
252 Dispersal probability (P_{disp}) responded non-monotonically to increasing G , shifting from high
253 median values and relatively large variances to very low median values with small variances
254 across a transition zone occurring between $G=0.05$ and $G=0.3$. This transition zone range was
255 affected by the Hurst index, with the transition starting earlier and declining somewhat more
256 mildly under a Hurst index of 1. From $G=0.3$ onwards, P_{disp} increased slightly with greater G .
257 Within this range, P_{disp} was slightly higher under a Hurst index of 1. Global dispersal probability
258 (P_{global}) was highly variable in nearly all scenarios and responded non-monotonically to increasing
259 G , initially decreasing around $G=0.1$ and then rebounding thereafter. This pattern was notably
260 stronger under a Hurst index of 1. Median P_{global} was consistently higher under a Hurst index
261 of 0.

262 0.4 Relationships between Organism Traits

263 Compositional heterogeneity and spatial autocorrelation affected the correlational relationships
264 between organism traits (Figure 2). Compositional heterogeneity had the strongest effect on
265 correlations between traits; spatial autocorrelation tended to mediate the strength of those cor-
266 relations. In scenarios with a Hurst index of 1, trait correlations tended to be slightly stronger,

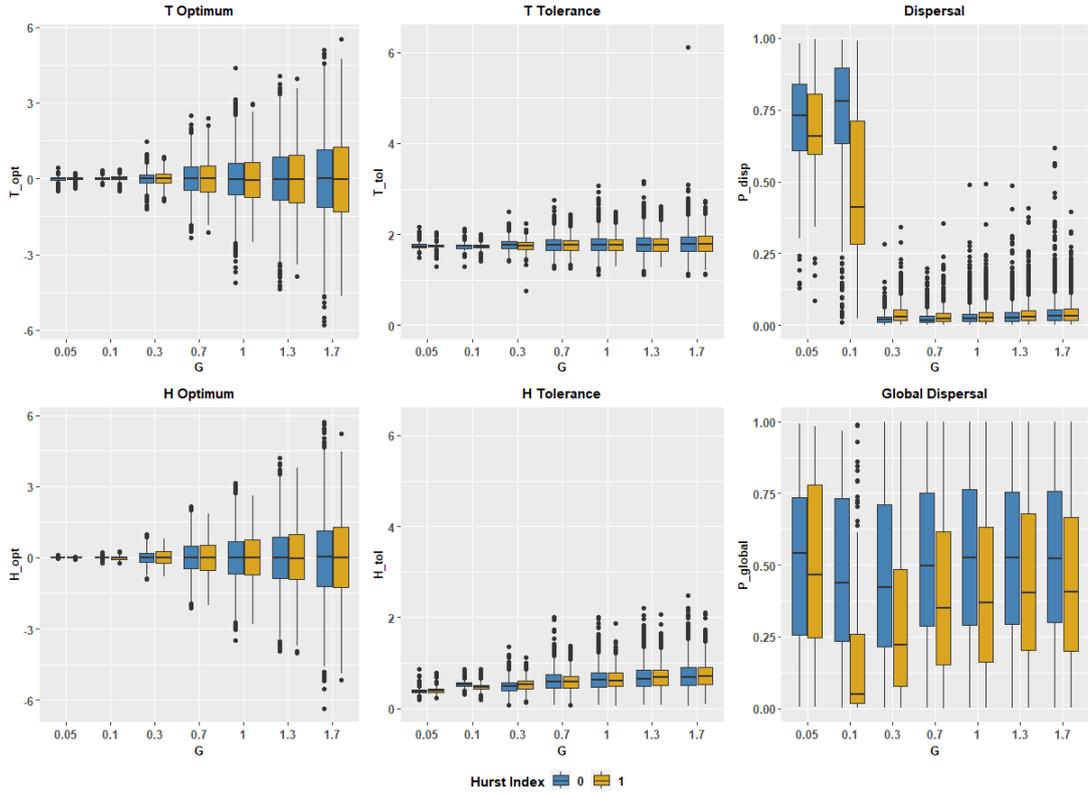


Figure 1. Box plot of distributions for organism trait values by G and Hurst index scenario at time step 10,000.

267 although this effect was not universal.

268 Trait correlations shifted between three distinct patterns as G increased. The first pattern
 269 occurred at $G=0.05$ and was characterized by strong but dramatically inconsistent relationships
 270 between traits. At $G=0.1$, this pattern gave way to a pattern characterized by negative cor-
 271 relations between absolute value niche optima (T_{opt} and H_{opt}), P_{disp} and positive correlations
 272 between P_{disp} , P_{global} , and H_{tol} . A negative correlation between P_{global} and absolute value niche
 273 optima traits occurred under a Hurst index of 1 under this pattern, but not under a Hurst index
 274 of 0. Further increases in G resulted in a shift to a third pattern characterized by positive asso-
 275 ciations between absolute value niche optima, P_{disp} , and H_{tol} , and negative associations between
 276 P_{disp} and P_{global} , and between P_{global} and absolute value H_{opt} . Additionally, under a Hurst index
 277 of 1 there was a slight but consistent negative relationship between P_{global} and H_{tol} while the
 278 relationship between P_{disp} and P_{global} was slightly stronger. Associations were typically stronger
 279 with absolute value H_{opt} than T_{opt} .

280 T_{tol} exhibited weak and inconsistent correlations with other traits across all scenarios, with a
 281 slightly higher tendency towards weak positive correlations with absolute value niche optima traits
 282 in Hurst index=0 scenarios at or above $G=0.3$. Correlations with T_{tol} tended to be strongest
 283 overall below $G=0.3$; in $G=0.1$ and $G=0.05$ scenarios, T_{tol} had a consistent negative correlation
 284 with P_{disp} .

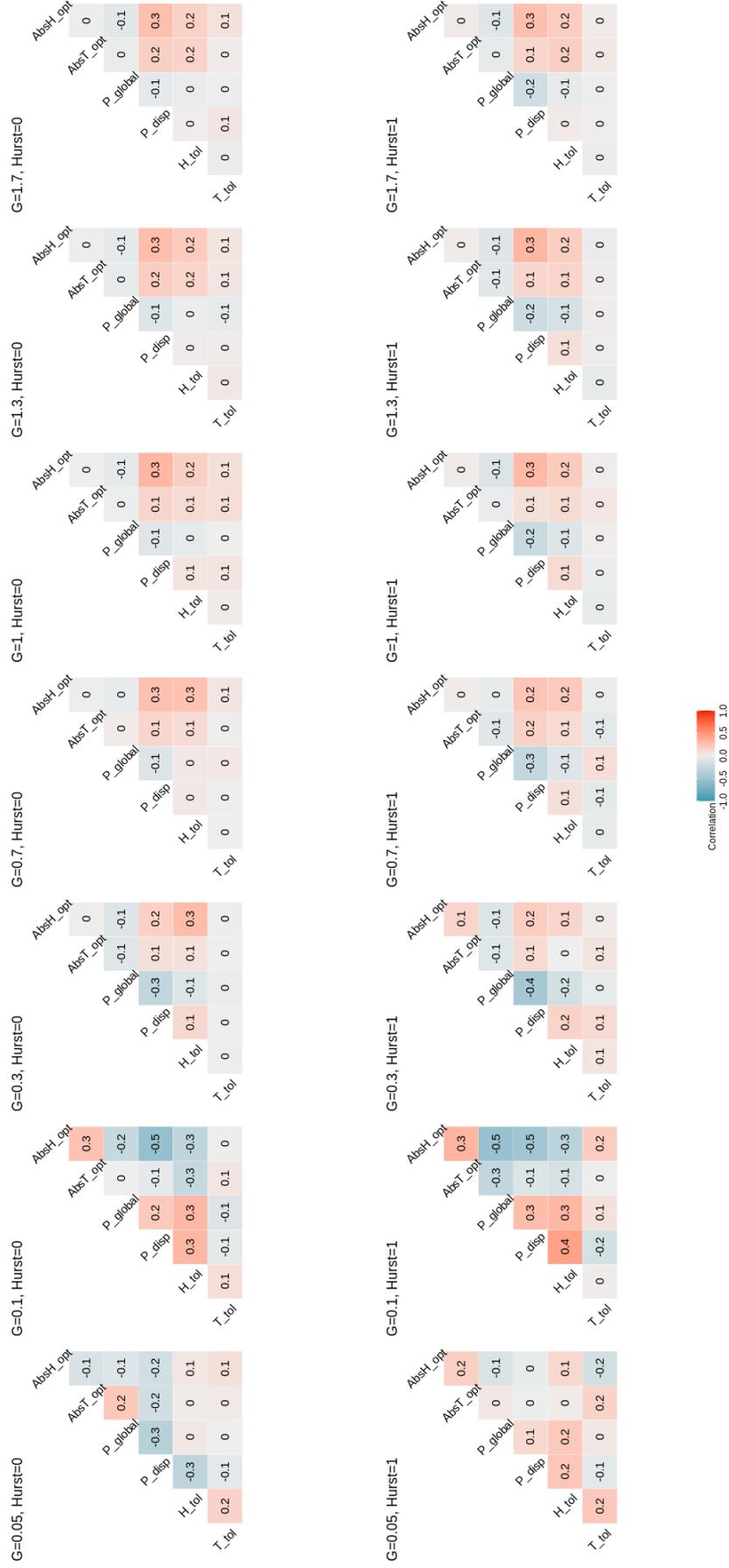


Figure 2. R^2 correlations between trait values by G and Hurst index scenario for individual organisms. Niche optima are absolute value transformed.

285 **0.5 Adaptation and Fitness**

286 Organisms were overall well adapted to their local patch conditions, with niche optima closely
 287 correlating with patch environment attributes. This correlation was strongest for H_{opt} , with T_{opt}
 288 tending to be more variable in relation to patch T (Figure 3). Species inhabiting more extreme
 289 patches had a tendency toward greater mismatches between niche optima and patch attributes;
 290 this pattern was stronger for the T attribute than the H attribute.

291 Accordingly, fitness was relatively high, with the vast majority of organisms having at over
 292 80% of their maximum fertility without accounting for reduced fertility due to the tolerance
 293 trade-off. Factoring in the tolerance trade-off, most individuals had expected at least 75% of
 294 their maximum fertility (Figure 3). Fertility declined slightly and increased in variance with
 295 increasing G .

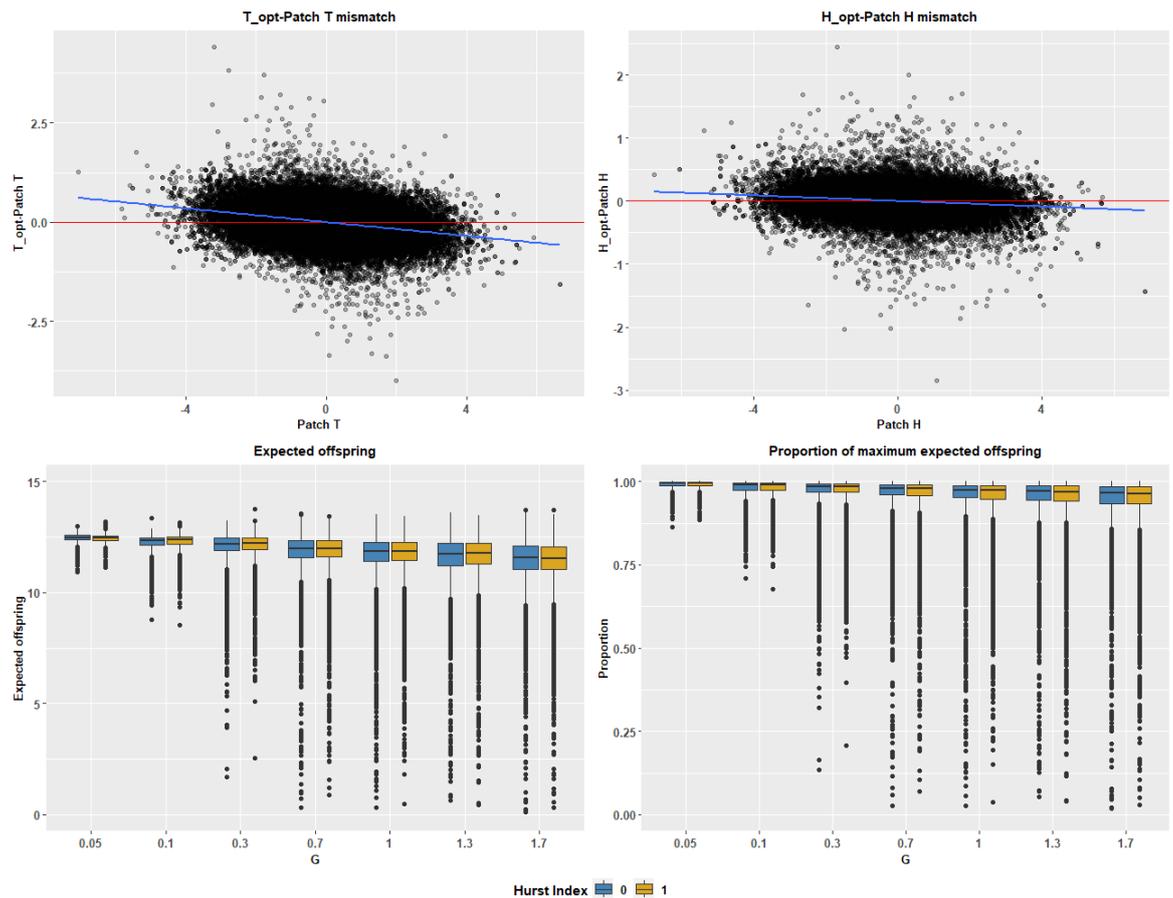


Figure 3. Individual local adaptation and fitness as measured by fertility. Top: Difference between individual niche optima and respective patch attributes vs. patch attribute. Bottom: Box plots of distributions at time step 10,000 by scenario of individual expected offspring and the proportion of maximum expected offspring, the expected number of offspring under optimal conditions.

296 Discussion

297 Landscape spatial structure affected niche traits and local adaptation, dispersal traits, and cor-
298 relational relationships between traits. Patterns were most strongly influenced by compositional
299 heterogeneity (G), with spatial autocorrelation (Hurst index) mostly playing a mediating role.
300 Dispersal traits were an exception to this and were notably affected by both compositional het-
301 erogeneity and spatial autocorrelation. Niche optima distributions reflected the distributions of
302 patch environment attributes in the landscapes and organisms were typically well adapted to their
303 local patches, in line with theoretical studies findings that greater spatial heterogeneity selects
304 for local adaptation due to the risk imposed by the landscape of immigrating into an unsuitable
305 habitat (Hastings, 1983; Futuyma and Moreno, 1988). Tolerance traits behaved differently for
306 the two environmental attributes. T tolerance was notably higher than habitat tolerance and was
307 weakly affected by landscape structure, resembling the results of Sieger and Hovestadt (2020),
308 and lacked any consistent relationships with other traits under most scenarios. H tolerance,
309 on the other hand, showed a clear relationship with landscape structure at both the patch and
310 landscape level. The difference in behavior of the two tolerance traits indicates that tolerance
311 is determined primarily by the degree to which environmental variation can be avoided. In this
312 model, and for many climate related environmental variables, temporal fluctuations are both
313 unpredictable and can occur synchronously over a large area and thus affect organisms indepen-
314 dently of spatial context or dispersal capabilities. Such environmental variation selects for broad
315 niches that permit consistent fitness over a large range of conditions (Lynch and Gabriel, 1987;
316 Futuyma and Moreno, 1988; Devictor et al., 2008; Lin and Wiens, 2017), potentially overriding
317 effects of smaller scale spatial variation. Purely spatial environmental variation, on the other
318 hand, can be avoided substantially by restricting movement and dispersal, allowing organisms to
319 retain more specialized niches.

320 Dispersal trait responses to compositional heterogeneity and spatial autocorrelation were non-
321 linear in nature and were largely consistent with established literature regarding relationships
322 between dispersal frequency, dispersal distance, and spatial heterogeneity (Burgess et al., 2016).
323 Dispersal shifted from a pattern of high dispersal probabilities at low levels of compositional
324 heterogeneity to very low dispersal probabilities once heterogeneity increased beyond a threshold
325 range, with slight increases in dispersal occurring at very high levels of compositional heterogene-
326 ity. Global dispersal probability shifted from a maximum at very low compositional heterogeneity
327 to a minimum around the threshold range at which dispersal probability shifted and rebounded
328 thereafter. Frequent dispersal is expected under very low spatial heterogeneity because there is
329 little spatial variation in fitness and thus little risk to dispersal, while kin competition imposes a
330 positive selection on dispersal (Hamilton and May, 1977; Nakajima and Kurihara, 1994; Gandon,

1999). Moreover, kin competition selects for longer dispersal distances as this allows organisms to minimize the chance of encountering kin in a destination patch (Hovestadt et al., 2001; Rousset and Gandon, 2002), resulting in a preference for random global dispersal under very low heterogeneity. Increasing compositional heterogeneity beyond a certain threshold resulted in a decline in dispersal chance across a transition zone as compositional heterogeneity began to exceed the limits of tolerances and impose increasingly significant fitness costs to dispersal (Hastings, 1983; Holt, 1985). This threshold itself was dependent on spatial autocorrelation and selection on dispersal traits within the transition zone was strongly divergent between autocorrelation scenarios. In the $G=0.1$ scenarios, high autocorrelation produced an extremely broad range of dispersal probabilities and the lowest global dispersal probabilities of any scenario, while dispersal trait distributions under low autocorrelation were similar to other low heterogeneity scenarios. The discrepancy between the two autocorrelation scenarios when $G=0.1$ is the result of several factors. Under low autocorrelation, unpredictable spatial variation selects for higher H tolerance, reducing risks associated with dispersal and making organisms less sensitive to spatial variance in the environment. In contrast, the predictability of spatial variation in highly autocorrelated landscapes results in lower H tolerance and thus greater sensitivity to spatial context. As a consequence, dispersal in the high autocorrelation $G=0.1$ scenarios is subject to a range of different selective pressures depending on an organism's environmental niche. Organisms adapted to common habitats, or those with broad tolerances face relatively low dispersal risks as suitable habitat is plentiful, while organisms with more narrow niches, or those adapted to rarer or more extreme environments face high risks when dispersing resulting in selective pressure toward lower dispersal probabilities. The predictability of spatial variation in high autocorrelation scenarios also strongly favors nearest neighbor dispersal over random global dispersal if dispersal is undirected, as it will almost always result in an organism landing in a suitable patch under moderate compositional heterogeneity, while random global dispersal carries significant risk of emigration into an unsuitable patch (Bonte et al., 2010). In the absence of spatial autocorrelation, there is no meaningful advantage to either dispersal method, causing global dispersal to behave as a largely neutral trait. At $G=0.3$ and above, spatial heterogeneity strongly selects for low dispersal probabilities; dispersal probabilities in these scenarios were similar to those observed by Sieger and Hovestadt (2020). Increases in dispersal and global dispersal probabilities with further increases in G above 0.3 indicate increasing selection for bet-hedging against temporal heterogeneity due to decreasing habitat area. Dispersal was slightly but consistently higher in highly autocorrelated scenarios at and above $G=0.3$ while global dispersal probability was consistently lower. These findings are consistent with the results of (Hovestadt et al., 2001), which also found that higher spatial autocorrelation favored increased local dispersal propensity and distance and disfavored global dispersal.

367 Patterns of correlation between traits responded in a non-linear fashion, with abrupt shifts in
368 patterns at two thresholds of compositional heterogeneity, one above $G=0.1$ and another thresh-
369 old below $G=0.1$. Above $G=0.1$, patterns were highly similar between scenarios, with absolute
370 value niche optima showing consistent positive relationships with tolerances and dispersal chance,
371 and a consistent negative relationship between dispersal chance and global dispersal that dimin-
372 ishes with greater heterogeneity. Meanwhile, patterns at $G=0.1$ were characterized by positive
373 associations between dispersal chance, global dispersal, and H tolerance, and negative associa-
374 tions between H tolerance and dispersal traits, and absolute value niche optima. These results
375 mirror those of Sieger and Hovestadt (2020), which found a shift in the location of the most fre-
376 quent dispersers from the most common habitats to rare patches with more extreme environments
377 as spatial heterogeneity increased, driven by greater selection for bet-hedging strategies in organ-
378 isms living in extreme patches. Similarly, trait correlation patterns in our model above $G=0.1$
379 are consistent with increasingly strong selection for bet-hedging strategies as niche optima move
380 further away from average landscape conditions. This is further supported by a pattern of lower
381 fitness in organisms adapted to more extreme conditions and the tendency for such organisms
382 to be adapted to slightly more average conditions than those they experienced in their habitat
383 patches. These patterns appear to be consequences of the smaller habitat area available to organ-
384 isms with more extreme niche optima. The small habitat area reduces the population sizes that
385 can be supported and renders such organisms particularly vulnerable to temporal environmental
386 fluctuations (Lande, 1993; Hanski, 1998; Hill and Caswell, 1999), increasing the importance of
387 risk spreading strategies for population persistence. The need for insurance against temporal
388 fluctuations may partly explain the slight tendency of "regression toward the mean" (Sieger and
389 Hovestadt, 2020) for niche optima in extreme patches as this apparent maladaptation may po-
390 tentially expand the number of patches an organism can survive in at any given time. Below
391 $G=0.1$, trait correlations became highly idiosyncratic and inconsistent. This is likely due to a
392 combination of very low variance in niche traits, weak selection within the range of values they
393 occupy, very weak selection on dispersal traits, and highly uneven landscape communities domi-
394 nated by a small number of lineages, leading to correlational patterns which are highly influenced
395 by stochasticity and priority effects.

396 This model makes a number of simplifying assumptions for ease of implementation, compu-
397 tation, and analysis which, if altered, could affect selection on traits and resulting trait patterns.
398 Our model assumes that organisms are asexual with an annual life cycle with no overlapping
399 generations and does not consider other life histories or reproductive strategies. Longer lifes-
400 pans allow for multiple bouts of reproduction which can serve to hedge reproductive bets in the
401 face of temporal by spreading reproduction out over time (Danforth, 1999; Hopper, 1999; Gre-
402 mer and Venable, 2014). Inclusion of competing annual semelparous organisms and perennial

403 iteroparous organisms would likely produce a pattern of succession over the course of the sim-
404 ulation with annual organisms dominating in the early stages and being gradually replaced by
405 perennial organisms as the simulation progresses. Longer lifespans may also have the effect of
406 reducing population turnover resulting in slower shifts in community level trait patterns. Inclu-
407 sion of overlapping generations, meanwhile, has the potential to alter selection on dispersal traits
408 as a result of the effect of age structure on kinship competition (Ronce et al., 2000). Including
409 dormancy would provide organisms, including organisms with annual, semelparous life cycles,
410 with an alternative means of hedging against reproductive risk by serving as a kind of dispersal
411 through time (Buoro and Carlson, 2014). As dormancy and dispersal serve similar bet hedging
412 functions, the addition of dormancy as a possible strategy would likely reduce dispersal frequency.
413 Organisms in our model are limited to two dispersal modes, and dispersal is assumed to be both
414 undirected and unaffected by an organism’s local environment or fitness. Undirected, uninformed
415 dispersal can incur a notable fitness cost due to the risk that an organism will emigrate to an
416 unsuitable patch or at an inopportune time (Hastings, 1983; Bonte et al., 2010), necessitating
417 greater tolerance which comes at the cost of maximum expected reproductive output in this
418 model. Informed and directed dispersal can greatly reduce dispersal risk related fitness costs,
419 particularly for long distance dispersal and under strong or unpredictable spatial environmental
420 variation (Lakovic et al., 2015; Sieger and Hovestadt, 2021). Reducing these fitness costs would
421 likely permit more frequent dispersal and a higher reproductive output due to reduced selection
422 for high tolerance. Finally, interactions with other organisms could affect selective pressures on
423 traits in a variety of complex ways (Chaianunporn and Hovestadt, 2012, 2019), but this model
424 only considers competition.

425 **Conclusions**

426 Our study systematically explored the role of compositional heterogeneity and spatial autocor-
427 relation in shaping both adaptation to environmental conditions and dispersal behavior in a
428 temporally variable environment, something which to our knowledge has not been systematically
429 explored by previous studies. Our model reproduced a number of patterns observed in previous
430 theoretical studies stemming from varying degrees of selective pressure imposed by the spatial and
431 temporal environments. We found that niche adaptation and dispersal patterns were primarily
432 driven by a balance between pressure to avoid risk imposed by spatial heterogeneity and pressure
433 to hedge against risk imposed by large scale temporal environmental fluctuations. Compositional
434 heterogeneity tended to have the strongest influence over patterns while spatial autocorrelation
435 typically played a mediating role. We found that dispersal frequency and dispersal distance were
436 affected differently by spatial structure, underscoring the need to consider the two independently.

437 Future studies should explore alternative life-history and dispersal scenarios, as well as exploring
438 how a shifting environment interacts with landscape spatial structure to influence patterns of
439 adaptation and dispersal behavior.

440 **Conflicts of interest**

441 The authors declare no conflicts of interest.

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447 **Author contributions**

448 J.T. and T.H. jointly conceptualized the model. J.T. implemented the model. J.T. and T.H.
449 analyzed the data. J.T. wrote the manuscript and created the figures and supplementary material.
450 T.H. reviewed and provided feedback on multiple drafts of the manuscript.

451 **Data Availability**

452 Simulation output data used in this manuscript as well as configuration files and shell scripts used
453 to run the simulations and the R scripts used for analysis are archived on the Dryad Digital Repos-
454 itory: doi:10.5061/dryad.mgqnk997t (Reviewer link: [https://datadryad.org/stash/share/
455 ZqHBR2sSrV_LUXcpjI9IP0HRne_ajU9xX70NWK6hrt4](https://datadryad.org/stash/share/ZqHBR2sSrV_LUXcpjI9IP0HRne_ajU9xX70NWK6hrt4)). Code for the simulation program used to
456 generate the data is available from GitHub: [https://github.com/jtardanico/TardanicoHovestadt2023_
457 Landscapes](https://github.com/jtardanico/TardanicoHovestadt2023_Landscapes).

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