# An Improved kT/C noise cancellation Tech-nique with Presampling for SAR ADCs

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#### Abstract

The kT/C cancellation technique can effectively reduce the DAC size for SAR ADCs and thus relax the burden for input drivers and ref-erence buffers. However, the prior kT/C cancellation technique suffers from a hard trade-off between the noise, amplifier bandwidth and linearity. In this work, an improved kT/C noise cancellation technique is proposed to break the trade-off. It uses presampling to hold the input signal unchanged during the noise cancelling phase, leading to sig-nificantly relaxed requirements on the bandwidth and linearity of the amplifier. The proposed technique is verified in a 14-bit 200MS/s SAR ADC with the DAC size of 128 fF. Simulation results show that this work achieves 75.6 dB SNDR and consumes 1.56 mW power.

## An Improved kT/C noise cancellation Technique with Presampling for SAR ADCs

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Introduction: The SAR is a popular ADC architecture with simple structure and low power. Aside from the ADC core, in practical applications, a SAR ADC often requires the front-end input driver and reference buffer, as shown in Fig. 1. However, limited by the sampling kT/C noise, the input capacitor of a SAR ADC has to be large to achieve high resolution. This makes it costly to design the input driver and reference buffer [1,2]. The kT/C cancellation technique can effectively reduce the DAC size for SAR ADCs, and thus relax the burden for input drivers and reference buffers [3,4]. However, the prior kT/C cancellation technique suffers from a hard trade-off between the noise, amplifier bandwidth and linearity, which is particularly serious in high-speed applications with high-frequency input signal. In this work, we propose an improved kT/C noise cancellation technique to break the trade-off.



### Fig.1 SAR ADC with input driver and reference buffer

Prior kT/C noise cancellation technique: The kT/C noise cancellation technique originates from the classic output series offset cancellation [5,6]. In [3], it is extended to a switched-capacitor amplifier which realizes the sampling noise reduction in an auto-zero manner. In [4], this technique is used in a SAR ADC. Comparing to [3], it reuses the SAR feedback to close the loop and only requires an open-loop amplifier. The SAR ADC with kT/C noise cancellation [4] is shown in Fig. 2. The sampling operation is divided into two phases,  $\Phi 1$ sampling (from t<sub>0</sub> to t<sub>1</sub>) and  $\Phi_2$  sampling (from t<sub>1</sub> to t<sub>2</sub>). During  $\Phi 1$  sampling, the input signal is tracked on the DAC C<sub>1</sub>, together with the thermal noise from sampling switches. After  $\Phi_1$  sampling, the sampling noise is frozen on C<sub>1</sub>. During the  $\Phi_2$  sampling phase, it is amplified and stored on C<sub>2</sub> through the amplifier. In this manner, the sampling kT/C<sub>1</sub> noise is cancelled at the right side of C<sub>2</sub>. Considering the limited bandwidth of amplifier, the kT/C<sub>1</sub> noise cannot be eliminated completely. The noise residue can be expressed as

$$\overline{v_{ns1,res}^2} = kT/C_1 \bullet e^{-2\Delta t/\tau}$$

where  $\Delta t$  is the time duration of  $\Phi_2$  sampling,  $\tau$  is the time constant at the output of amplifier.

To reduce noise, one way is to increase  $\Delta t$ , but this can degrade the linearity of amplifier and even cause saturation because the input signal change during  $\Delta t$  is also amplified. To ensure linearity, the signal change at the amplifier input must be small. As a result, the input signal frequency is limited. Another way is to reduce the time constant  $\tau$  by increasing amplifier bandwidth, but this is at the cost of increased power. Even if the power budget is sufficient, the bandwidth improvement will be eventually prevented by input transistor size of the amplifier. This is because the large input capacitance of amplifier exaggerates the ADC input-referred noise.

As analyzed above, for the ADCs with kT/C noise cancellation, the signal bandwidth is limited by the trade off between noise, amplifier bandwidth and linearity. The root cause of this issue is that the amplifier has to deal with the input signal change during  $\Phi_2$  sampling phase.





Fig.2 Previous SAR ADC with kT/C noise cancellation

Proposed kT/C noise cancellation SAR ADC with presampling: To break the trade-off, this work proposes an improved kT/C noise cancellation technique with presampling [7]. On top of Fig. 2, an additional switchcapacitor pair,  $\Phi_0$ -C<sub>0</sub>, is introduced. C<sub>0</sub> acts as a presampling capacitor, which samples the input signal and holds it during the  $\Phi_2$  sampling phase.





## **Fig.3** Proposed kT/C cancellation SAR ADC with presamping

The detailed operation of the proposed kT/C cancellation technique is illustrated in the following:

- 1.  $\Phi_0$  sampling: during  $\Phi_0$  is high, the input signal is tracked on  $C_0$ .
- 2.  $\Phi_1$  sampling: at the final stage of  $\Phi_0$  sampling,  $\Phi_1$  turns on and the input signal is also tracked on  $C_1$ . Then,  $\Phi_0$  and  $\Phi_1$  turns off in sequence, and the input signal is sampled on  $C_0$  and  $C_1$ .
- 3.  $\Phi_2$  sampling: during  $t_1$  to  $t_2$ , the kT/C<sub>1</sub> noise is amplified and stored on C<sub>2</sub>, which is same as that in [4]. The difference is that there is no input signal change but only the sampled noise at the input of amplifier, because the input signal at the bottom plate of C<sub>1</sub> is hold constantly by C<sub>0</sub>. This eliminates the issues of amplifier saturation and nonlinearity existing in [4]. Therefore, the relatively long  $\Delta t$  and large amplifier gain can be used to suppress the kT/C<sub>1</sub> noise and amplifier noise, respectively.

Comparing to [4], the additional  $C_0$  sampling operation and the  $kT/C_0$  noise are introduced. Since the  $C_0$  sampling noise is not cancelled, a large-size kT/C determined  $C_0$  capacitor is required. Nevertheless, the reason abilities and merits of the proposed technique lies in the following aspects:

- 1. Although a large  $C_0$  is required, a long  $C_0$  sampling time can be allocated to relax the burden of input driver. As shown in Fig. 3, all the time expect  $\Delta t$  can be used for  $C_0$  sampling.
- 2. As with [4], the kT/C<sub>1</sub> noise is canceled and thus small DAC can be used to reduce the load for reference buffer.
- 3. Comparing to [4], this technique suffers no amplifier nonlinear issues, and thus the long  $\Delta t$  and large amplifier gain can be used. This further reduces the  $kT/C_1$  noise and amplifier noise, and also relaxes the requirement on amplifier bandwidth.

Circuit Implementation and Simulation results: A14-bit SAR ADC with the proposed kT/C noise cancellation is designed in a 28nm CMOS process. As shown in Fig. 4, C<sub>0</sub> is 2.8 pF and DAC C<sub>1</sub> is 128 fF. The gain of the amplifier is about 10. The time duration of  $\Delta t$  is 25% of an entire ADC cycle. In comparison, the amplifier gain is 6 and  $\Delta t$  is 2.5% of an ADC cycle in [4]. The increased  $\Delta t$  can relax the amplifier bandwidth requirement.







Fig.4 Circuit implementation of the proposed SAR ADC.

Fig. 5 shows the simulated output spectrum. Operating under 1 V supply and 200 MHz sampling rate, the simulated SNDR is 75.6 dB with a 98 MHz input signal. The total power consumption is 1.56mW. This leads to a superior Schreier Figure of Merit (FoMs) of 183.7 dB. The noise and power breakdown are provided in Fig. 6. It shows that 41% of the total power is consumed by the amplifier, 12% by the DAC, 40% by digital circuits and 7% by others. The total noise is 13.7nV2, with 40% from the amplifier, 23% from  $kT/C_0$  noise, 16% from  $kT/C_1$  noise, 9% from quantization noise and 12% from others.

## Hosted file

image17.emf available at https://authorea.com/users/813439/articles/1214823-an-improved-ktc-noise-cancellation-tech-nique-with-presampling-for-sar-adcs

Fig.5 Simulated spectrum.

Fig.6 Noise and power breakdown.

(a)

(b)

Fig.7 Simulation results of the sampling circuits in (a) traditional SAR ADC and (b) proposed SAR ADC

Fig. 7 compares the simulated voltage and current waveforms of the sampling circuits in a conventional SAR ADC and the proposed one. For a conventional SAR ADC, in order to leave as much as time to SAR conversion, typically the tracking phase occupies a small portion of an entire ADC cycle. As shown in Fig. 7(a), 13% of an entire ADC cycle is used for tracking. For a near-Nyquist input signal, the maximum input signal change ( $\Delta V_{max}$ ) on the sampling capacitor is as high as 990 mV and the peak current ( $\Delta I_{max}$ ) drawn from the input buffer is 44.3 mA. In contrast, for the proposed ADC, the most of an ADC cycle can be allocated for tracking. As shown in Fig. 7(b), 87% of an entire ADC cycle is used for tracking, leading to a short time of disconnection between the input driver and the sampling capacitor. This makes the proposed ADC close to a continuous-time one. Comparing to Fig. 7(a), the maximum input signal change ( $\Delta V_{max}$ ) on the sampling capacitor and the peak current ( $\Delta I_{max}$ ) are significantly reduced to 256.3 mV and 15.1 mA, respectively. This verifies that the long tracking time can relax the requirement on the driving capability of input buffer.

Conclusion: This work proposes an improved kT/C noise cancellation technique with presampling for SAR ADCs. Comparing to the previous works [4], the proposed technique effectively addresses the nonlinear issues and relaxes the bandwidth requirement of the amplifier, leading to the improved accuracy and reduced power. Comparing to the conventional SAR ADCs, it greatly increases the tracking time and reduces the DAC size, leading to relaxed burden for the input drivers and reference buffers.

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